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KRIS HAUSER - Duke University

the Algorithm Foundations of Robotics (WAFR), 2008 (Also published in Algorithmic Foundations of Robotics VIII, Springer Tracts in Advanced Robotics (STAR), Springer Berlin / Heidelberg, vol 57, p615-630, 2010) 30 V Ng-Thowhing, E Drumwright, K Hauser, Q Wu, and J Wormer, Expanding Task Functionality in Established Humanoid Robots

Simultaneous Control of Multiple MEMS Microrobots

GS Chirikjian et al (Eds): Algorithmic Foundations of Robotics VIII, STAR 57, pp 69-84 Simultaneous Control of Multiple MEMS Microrobots 71 2 Related Work Small, often completely autonomous mobile robotic devices, with size on the order Simultaneous Control of Multiple MEMS Microrobots 73 4 STRING Theory: Control Signal Design

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584 W Park, Y Wang, and GS Chirikjian medical treatments [1, 2, 7, 12, 17] In this problem, a flexible needle is rotated with the angular speed $\omega(t)$ around its tangent while it is inserted with translationalspeed $v(t)$ in the tangential directionDue to the bevel tip, the needle will not fol-

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Plane for Monocular Vision-Based Robot Navigation, Algorithmic Foundations for Robotics VIII, Springer tracts on advanced robotics, Springer, 2008
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On Approximate Geodesic-Distance Queries amid Deforming Point Clouds Pankaj K Agarwal, Alon Efrat, R Sharathkumar, and Hai Yu Abstract We propose data ...

IGOR PAPROTNY - UIC

I Paprotny (1/3/2017) 4 1 Authors are listed in alphabetic order - lead researcher is underlined DS Nguyen, P Pillatsch, I Paprotny, P Wright, and R White, "MEMS Flow Sensors with Silicon-Carbide Erosion Resistant Coating," in the Proceedings of the 14th Annual IEEE Conference on Sensors (IEEE SENSORS 2015), pp 991-994, 1-4 Nov 2015

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